

Special considerations for TwinSAR-L baseline calibration method with known heights of point targets or reference DEM

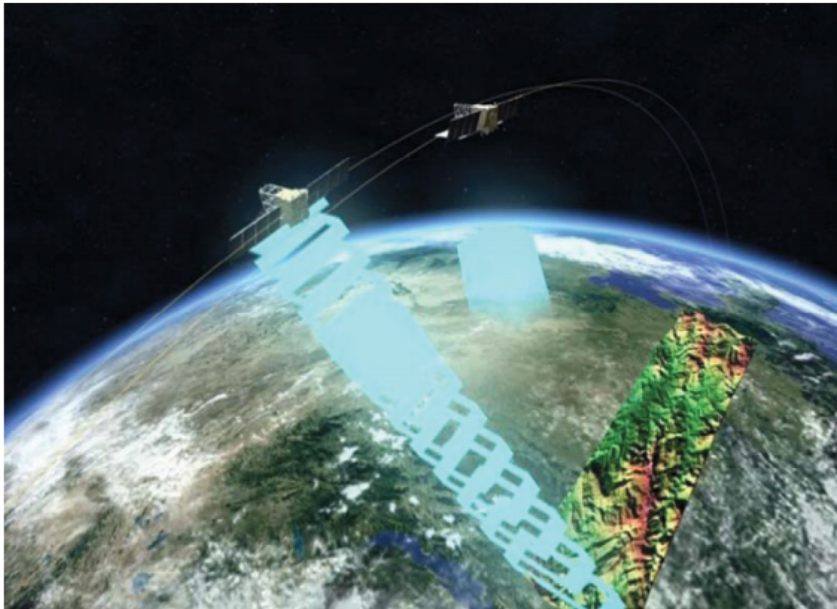


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Science and Technology on Microwave Imaging Lab.
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Outline

- **TwinSAR-L System Overview**
 - TwinSAR-L interferometry Mode & parameter
 - InSAR height measurement principle
- **Distributed target baseline Calibration method overview**
- **Special considerations for TwinSAR-L**
 - Penetration depth
 - Signal to Noise Ratio
- **Summary**
- **Future work**

TwinSAR-L System Overview



Artists view of the TwinSAR-L satellites flying in close formation

Items	Value
Orbit Height(km)	607
Orbit semi major axis(km)	6978
Frequency(GHz)	1.26
Antenna length(m)	10
Orbit inclination(deg.)	97.8
Baseline calibration requirement(mm)	12
Relative height accuracy(m)	5

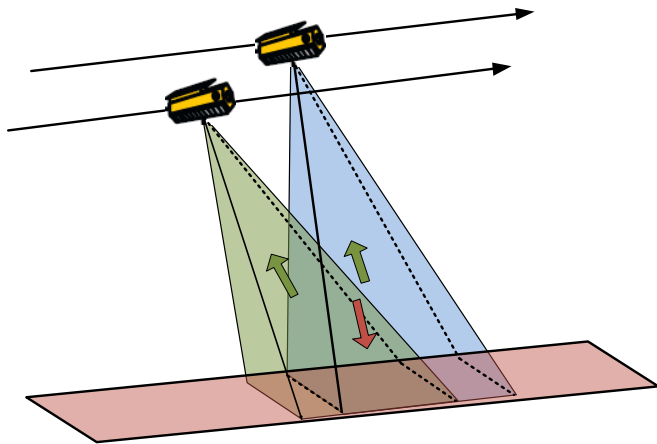
PARAMETERS OF THE SYSTEM

- TwinSAR-L(LT-1) mission was established in 2016 and will be launched in 2020.
- Multiple modes : single-pass interferometry, multi-pass interferometry, multi polarization and wide swath imaging.

Ref: C. Li et al., "Focusing the L-Band Spaceborne Bistatic SAR Mission Data Using a Modified RD Algorithm," IEEE TGRS.doi: 10.1109/TGRS.2019.2936255.

TwinSAR-L interferometry Mode:

➤ the Helix satellite formation

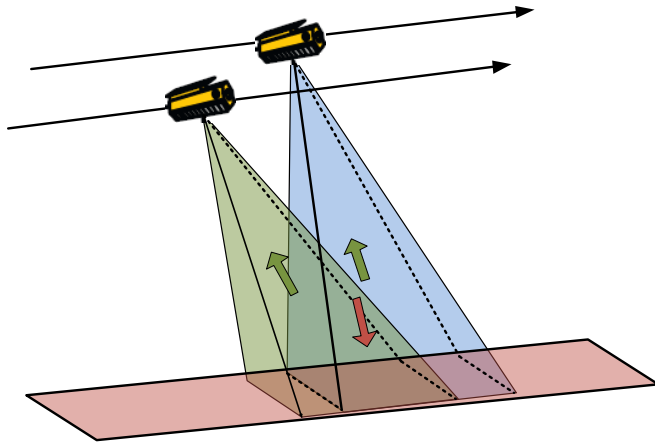


➤ interferometry Mode parameter

Items	Value
Ground range resolution(m)	3
Azimuth resolution(m)	3
Baseline length(km)	4~6
Incident angle (deg.)	20~46
Swath Width(km)	50

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interferometry Mode parameter

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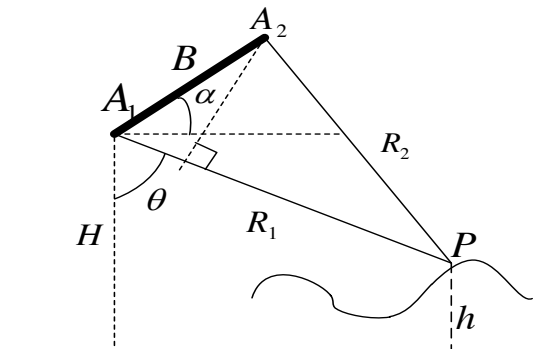
InSAR height measurement principle

$$\cos(90^\circ - \theta + \alpha) = \sin(\theta - \alpha) = \frac{B^2 + R_1^2 - R_2^2}{2B \cdot R_1}$$

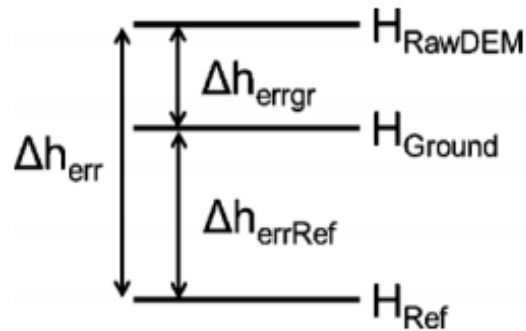
$$\phi = \frac{2\pi(R_1 - R_2)}{\lambda}$$

$$(R_1 - R_2) \simeq B \cdot \cos(90^\circ - \theta + \alpha) = B \cdot \sin(\theta - \alpha)$$

$$h = H - R_1 \cos\theta$$



Distributed target baseline Calibration method overview

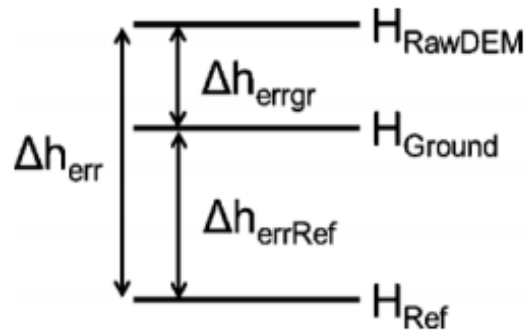


$$\Delta h_{err} = H_{RawDEM} - H_{Ref}$$

$$\Delta h_{errgr} = H_{RawDEM} - H_{Ground} = \frac{\Delta\phi}{2\pi} H_{amb}$$

$$\Delta h_{errRef} = H_{Ref} - H_{Ground}$$

Distributed target baseline Calibration method overview



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$$\Delta h_{errRef} = H_{Ref} - H_{Ground}$$

$$\Delta h_{err} = \frac{r \sin \theta_i}{B_{\perp}} \cdot B_{\parallel err} = \frac{H_{amb}}{\lambda} \cdot B_{\parallel err}$$

$$B_{\parallel err} = \frac{\Delta\phi}{2\pi} \lambda - \frac{\Delta h_{errRef}}{H_{amb}} \lambda.$$

$$\vec{B}_{BIAS} = \vec{B}_{\parallel err1} + k_1 \cdot \hat{B}_{\perp1} = \vec{B}_{\parallel err2} + k_2 \cdot \hat{B}_{\perp2}$$

Ref: Antony J W , et al. Results of the TanDEM-X Baseline Calibration . IEEE J-STARS, 2013, 6(3):1495-1501.

Two considerations for TwinSAR-L baseline calibration method with known heights from laser altimeter

Two considerations for TwinSAR-L baseline calibration method with known heights from laser altimeter

- **The height error caused by penetration depth**
- **The height error caused by Signal to Noise Ratio(SNR)**

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- **The height error caused by penetration depth**
- **The height error caused by Signal to Noise Ratio(SNR)**



simulation

Simulation : penetration depth

Ulaby penetration depth model(while $\frac{\epsilon''}{\epsilon'} < 0.1$)

$$\delta_P = \frac{\lambda \sqrt{\epsilon'}}{2\pi\epsilon''}$$

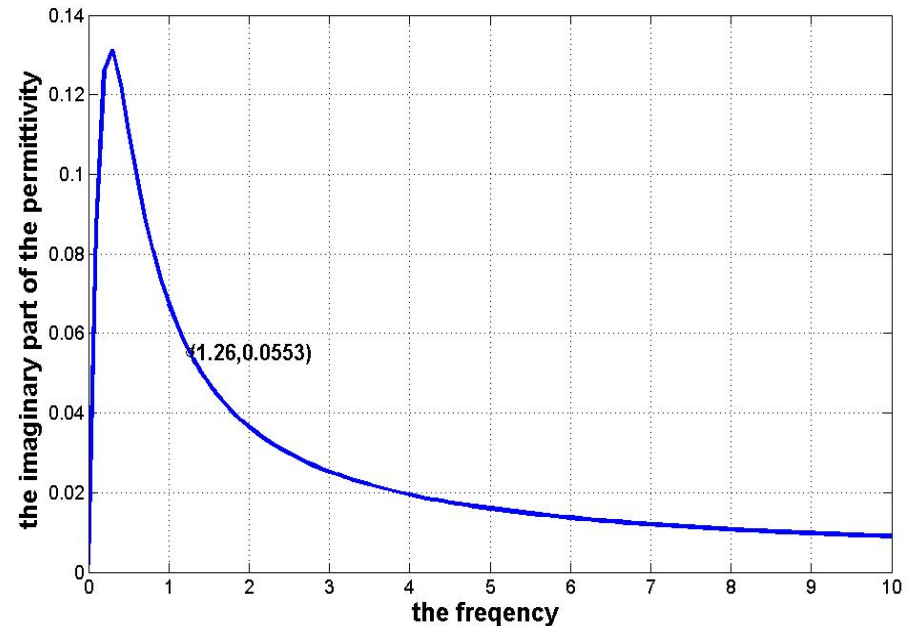
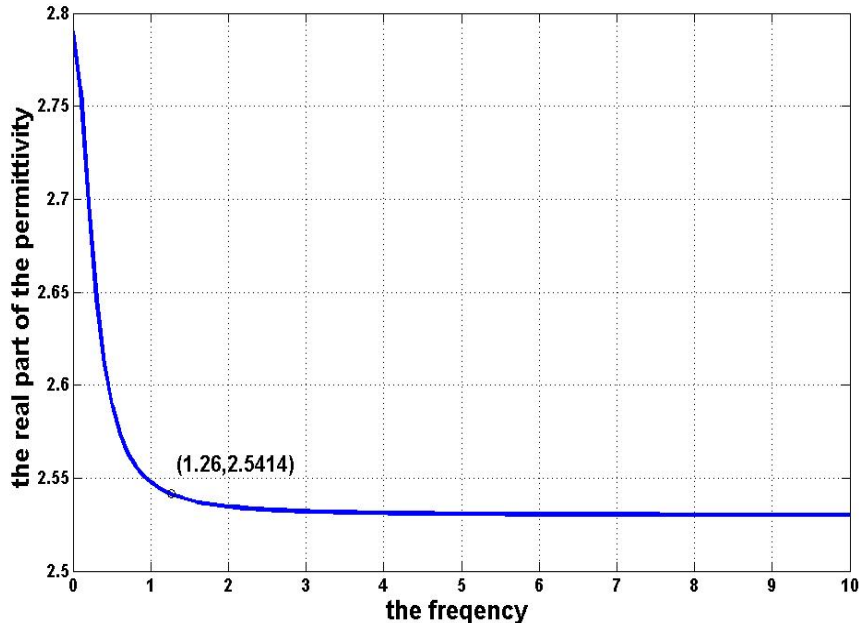
λ is wavelength and ϵ' , ϵ'' are the real part and the imaginary part of the soil's permittivity

Ref: Ulaby F T , et al. Radar polarimetry for geoscience applications Norwood. MA: Artech House, 1990

Simulation : penetration depth

Permittivity model:

$$\varepsilon = \varepsilon' + i \cdot \varepsilon'' = \varepsilon_{\infty} + \frac{(\varepsilon_s - \varepsilon_{\infty})}{1 - \frac{if}{f_0}} + ia'' \quad f \in (0.245GHz, 6GHz)$$



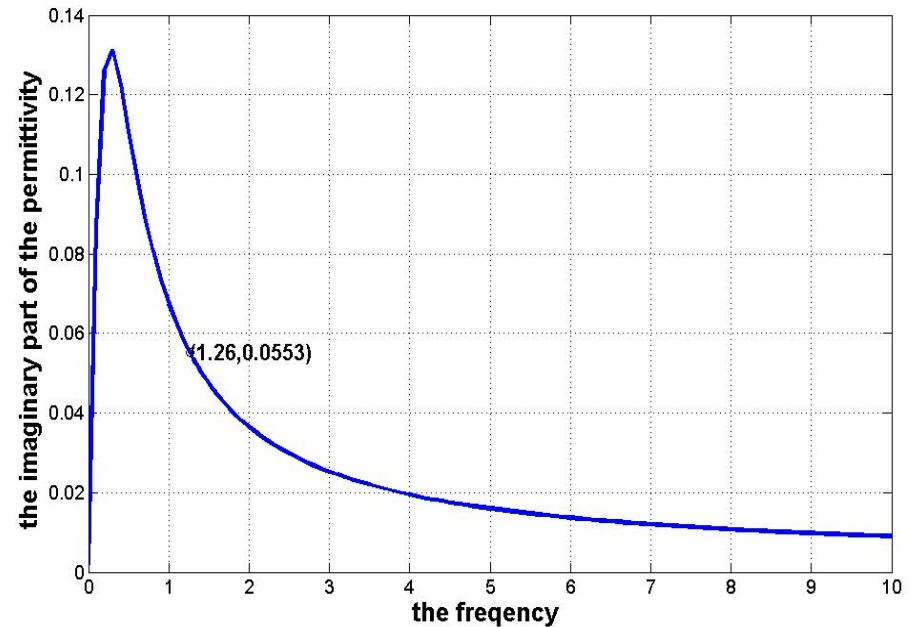
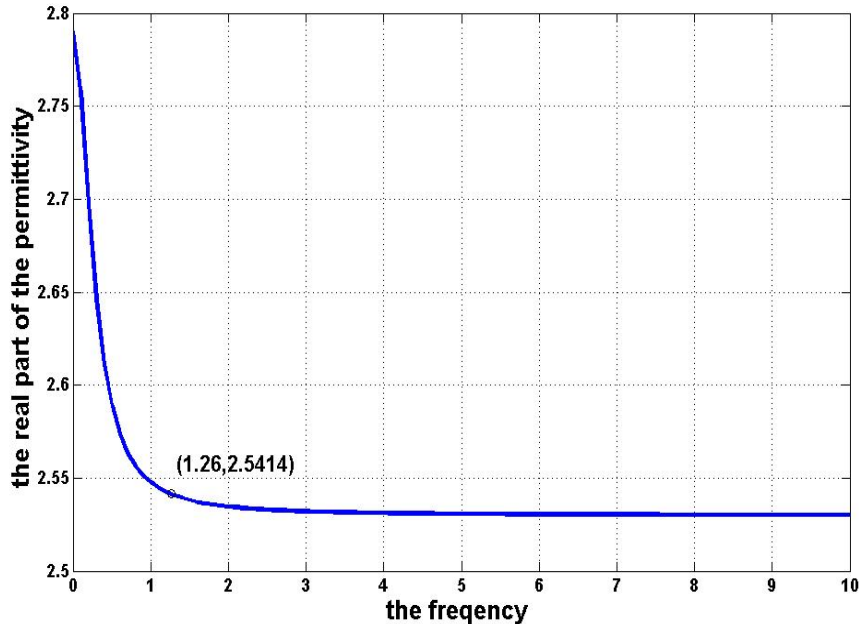
Ref: Christian Matzler, C. Microwave permittivity of dry sand. IEEE TGRS 1998, 36(1):0-319.

Ulaby F T , et al. A Backscatter Model for a Randomly Perturbed Periodic Surface. IEEE TGRS, 1982, 20(4):518-528.

Simulation : penetration depth

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According to the figures: the permittivity in L band is (2.5414, 0.0553)

Simulation : penetration depth

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$$\delta_P = \frac{\lambda \sqrt{\epsilon'}}{2\pi\epsilon''}$$

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the permittivity of dry sand in L band is (2.5414 , 0.0553)



put the data into the model:

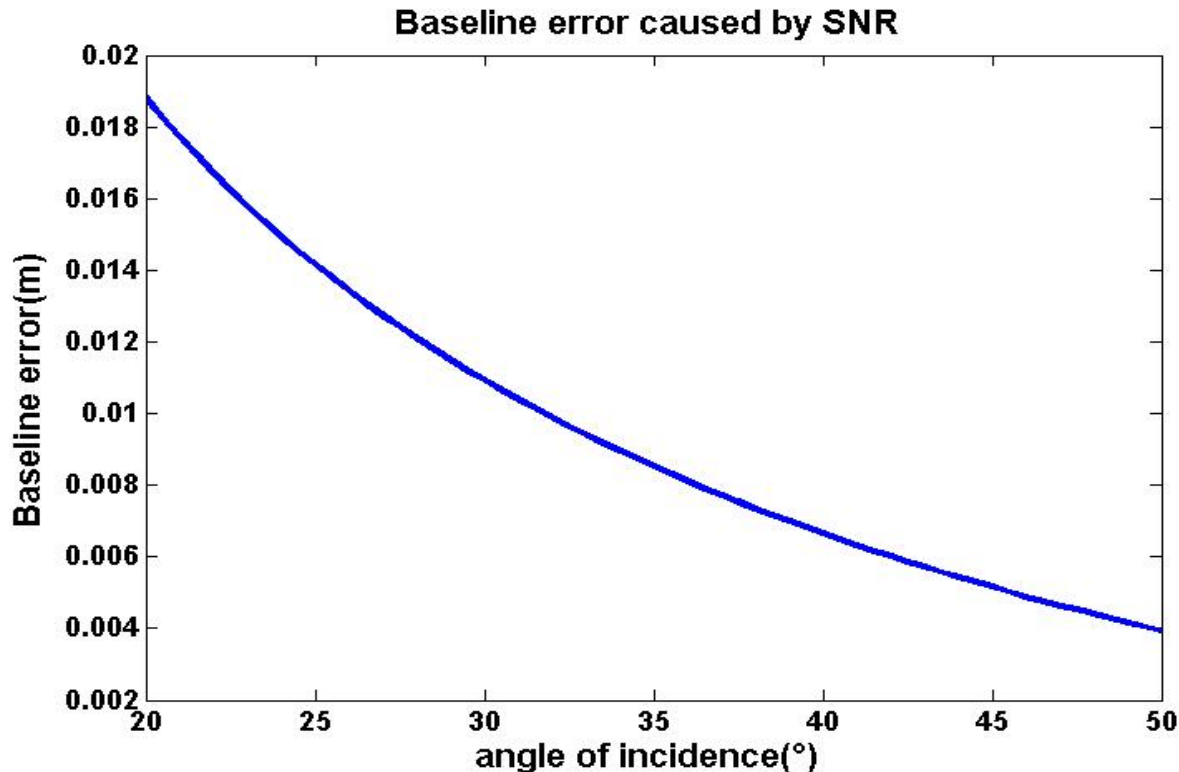
$\delta_1 = 1.0924\text{m}$ (penetration depth in L band)

Height error is 1.0924m (required 5m)

Simulation : penetration depth

Height error is **1.0924m(required 5m)**

$$B_{\parallel err} = \frac{B_{\perp}}{r \sin \theta_i} \cdot \Delta h_{err}$$



Baseline error :**3.9mm to 18.8mm(required 12mm)**

Simulation : penetration depth



Parameter		Test result				
		bare land	grassland	cement court	sand land	
land surface parameter	humidity (%)	1.24	15.53	0.11	0.25	
	average temperature (°c)	32	32	34	28	
	average wind speed(m/s)	3.94	4.22	6.43	5.32	
	rms height (cm)	2.23	-	0.082	-	
	correlation length (cm)	50.2	-	5.68	-	
	Relative complex permittivity	1.34GHz	4.85,0.0196	-	-, -	2.98,0.068
		3.2GHz	4.86,0.021	-	-, -	2.96,0.073
10GHz		4.75,0.023	-	-, -	2.89,0.078	
16 GHz		4.69,0.025	-	-, -	2.86,0.081	

the permittivity of dry sand in L band is (2.98 , 0.068)
 the permittivity of dry sand in X band is (2.89 , 0.078)

**the experimental data provided by CRIRP in 2009
 (Institute of radio propagation in China)**

Simulation : penetration depth



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Put the data into the Ulaby penetration depth model:

$$\delta_1 = 0.9046m \quad (\text{penetration depth in L band})$$

$$\delta_2 = 0.1041m \quad (\text{penetration depth in X band})$$

Baseline error (L): 3.3mm to 15.6mm (required 12mm)

Baseline error (X): 0.37mm to 1.8mm (required 12mm)

Simulation : backscattering coefficient

γ - f backscattering coefficient model

$$\sigma_{r-f}^0 = \gamma \cdot a f^b \cdot \sin(\psi + c)$$

f is the frequency(GHz); ψ is depression angle; a, b, c and γ are Coefficients based on statistical methods

The relevant parameters under various terrains :

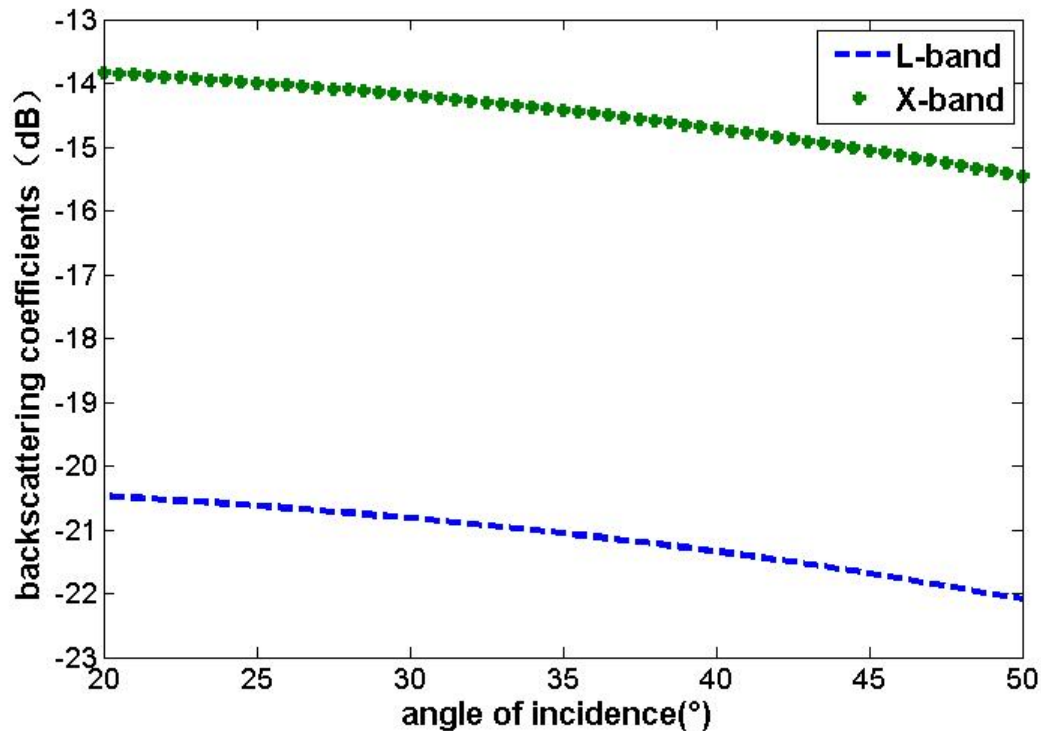
terrains	γ	a	b	c
sand land	0.1	0.08	0.75	0.50
farmland	0.0316	0.18	0.60	0.55
hill	0.1	0.25	0.20	1.20
Urban	0.316	0.35	0.18	0.70

Simulation : backscattering coefficient

γ - f backscattering coefficient model:

$$\sigma_{r-f}^0 = \gamma \cdot a f^b \cdot \sin(\psi + c)$$

γ - f backscattering coefficient Simulation result:



Simulation : backscattering coefficient

Height error caused by the Signal to Noise Ratio :

Signal to Noise Ratio:

$$SNR(dB) = \sigma^0(dB) - NE\sigma^0(dB)$$

Correlation:

$$\gamma = \frac{1}{1 + SNR^{-1}}$$

Phase Noise:

$$\sigma_\phi = \frac{1}{\sqrt{2N}} \frac{\sqrt{1-\gamma^2}}{\gamma}$$

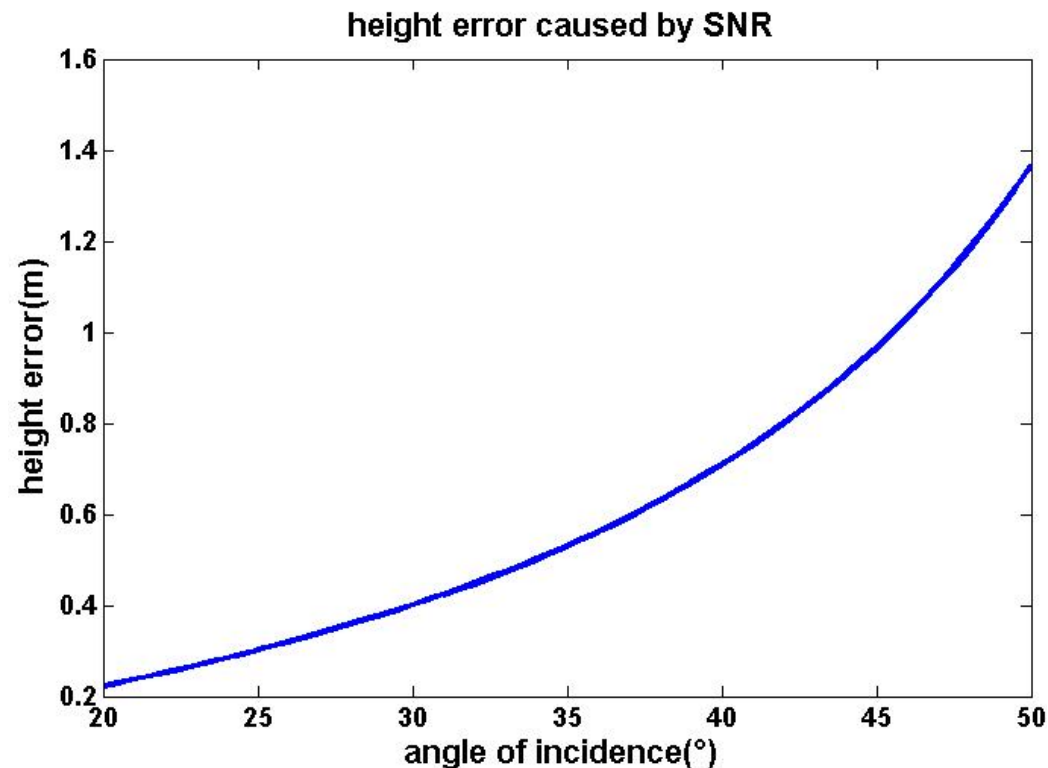
Height error:

$$h_{err} = \frac{h_{amb}}{2\pi} \sigma_\phi = \frac{\lambda r \sin(\theta_i)}{2\pi B_\perp} \sigma_\phi$$

Baseline error:

$$B_{\parallel err} = \frac{\lambda h_{err}}{h_{amb}}$$

Height error : 0.22m to 1.37m (required 5m)
Baseline error : 3.8mm to 4.9mm (required 12mm)



Simulation : backscattering coefficient

The modified Morchin backscattering coefficient model:

$$\sigma^0 = \frac{A\sigma_c^0 \sin\theta_g}{\lambda} + u \cot^2 \beta_0 \exp\left[-\frac{\tan^2(B - \theta_g)}{\tan^2 \beta_0}\right]$$

$u = \frac{\sqrt{f_0}}{4.7}$, f_0 (GHz) is the frequency; θ_g is depression angle; the terrain is sand land; if $\theta_g < \theta_c$, $\sigma_c^0 = (\frac{\theta_g}{\theta_c})^k$ else if $\theta_g > \theta_c$, $\sigma_c^0 = 1$; $h_e \approx 9.3\beta_0^{2.2}$; $k=1$; A, B, β_0 are Coefficients based on statistical methods:

The relevant parameters under various terrains :

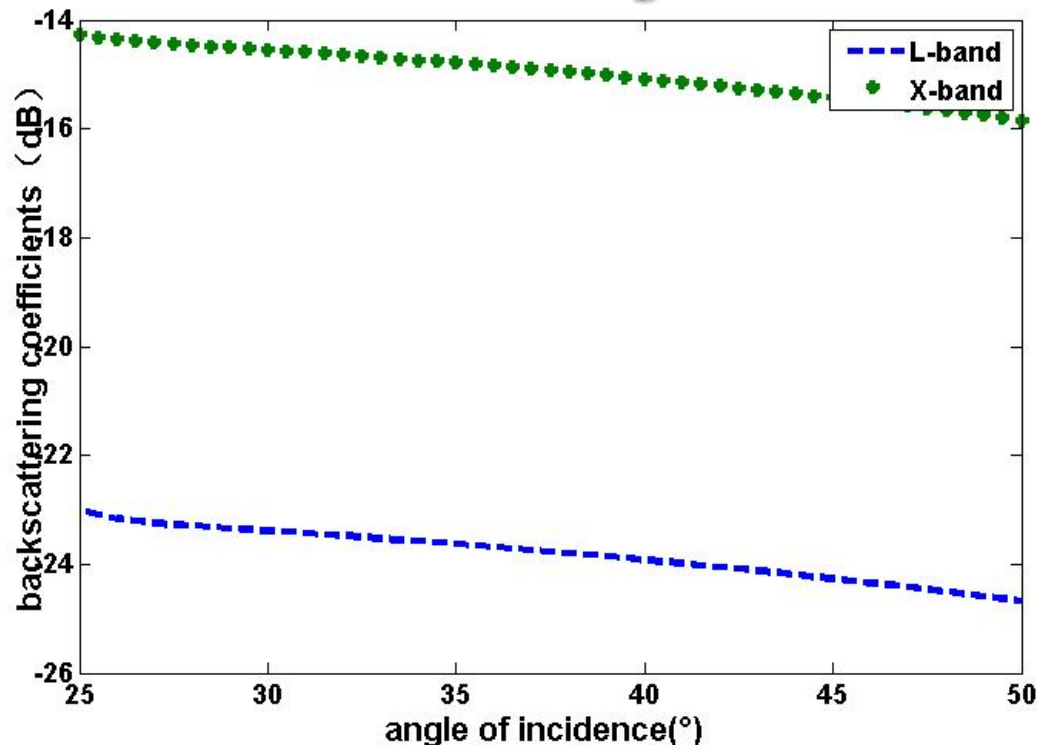
terrains	A	B	β_0	σ_c^0
sand land	0.00126	$\pi/2$	0.14	θ_g/θ_c
farmland	0.004	$\pi/2$	0.2	1
hill	0.0126	$\pi/2$	0.4	1
mountain	0.04	1.24	0.5	1

Simulation : backscattering coefficient

The modified Morchin backscattering coefficient model:

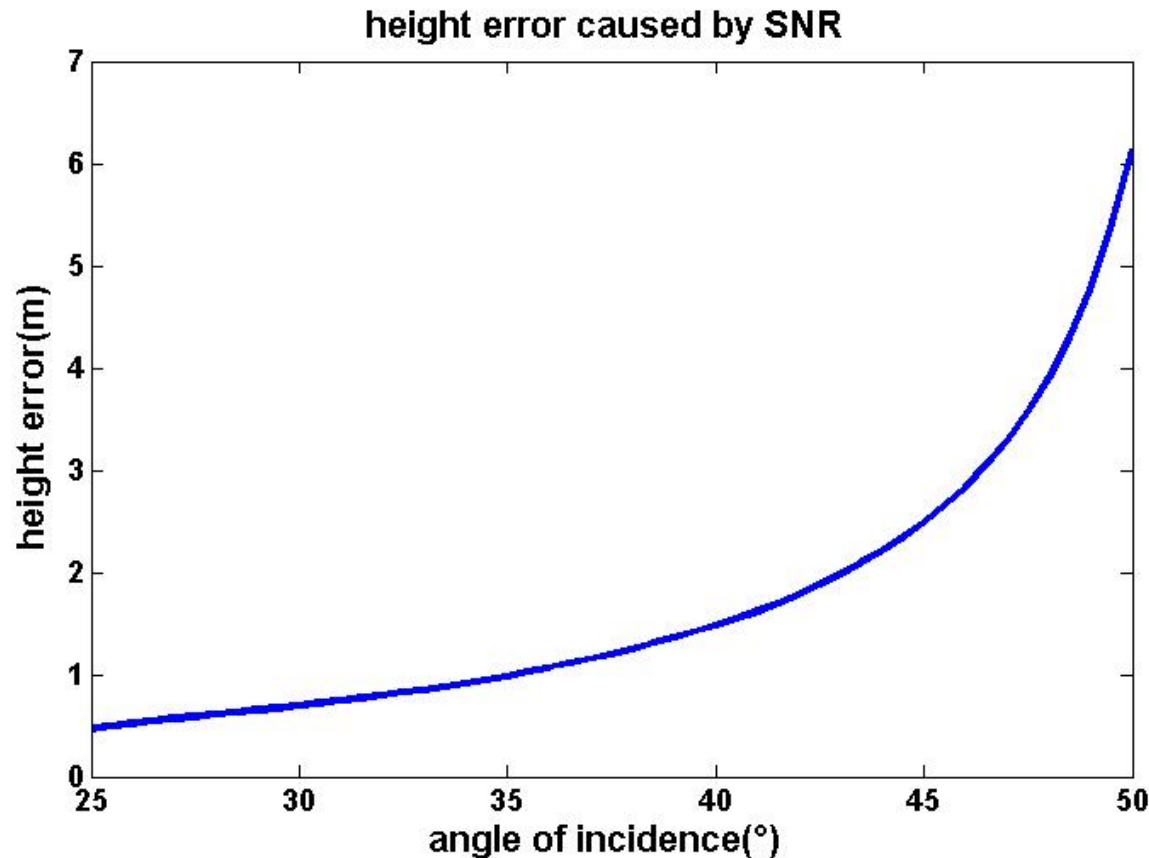
$$\sigma^0 = \frac{A\sigma_c^0 \sin\theta_g}{\lambda} + u \cot^2 \beta_0 \exp\left[-\frac{\tan^2(B - \theta_g)}{\tan^2 \beta_0}\right]$$

The modified Morchin backscattering coefficient Simulation :



Simulation : backscattering coefficient

Height error caused by the Signal to Noise Ratio :



Height error : **0.47m to 6.13m(required 5m)**

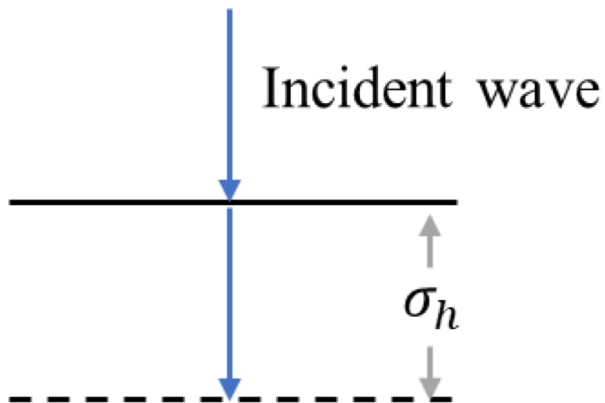
Baseline error : **6mm to 24mm(required 12mm)**

Summary

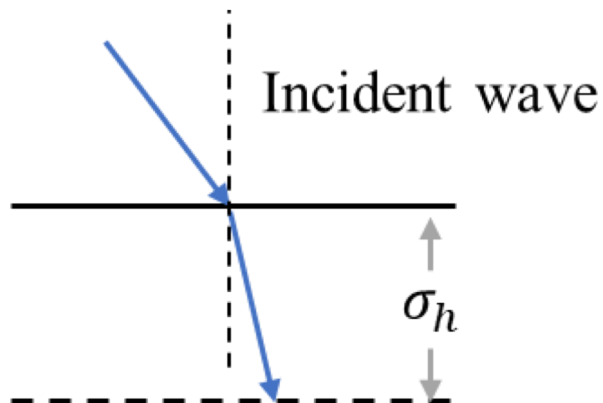
- **Height error caused by penetration depth in L band is around 1.0m(required 5m) and Baseline error ranges from 3.9mm to 18.8mm (required 12mm)**
- **Height error caused by SNR in L band in γ - f backscattering coefficient model ranges from 0.22m to 1.37m (required 5m) and Baseline error ranges from 3.8mm to 4.9mm (required 12mm)**
- **Reference DEM is replaced by point targets for the baseline calibration of TwinSAR-L.**

Future work

- **Validation with The L-Band ALOS-2 satellite data.**
- **The refraction at the interface will be considered.**



**Refraction at the interface
isn't considered**



**Refraction at the interface
is considered**

Institute of Electrics(IE),
Chinese Academy of Sciences(CAS)

Thank you for your attention!

